

Simulating Time With Square-Root Space



image courtesy of DALL-E

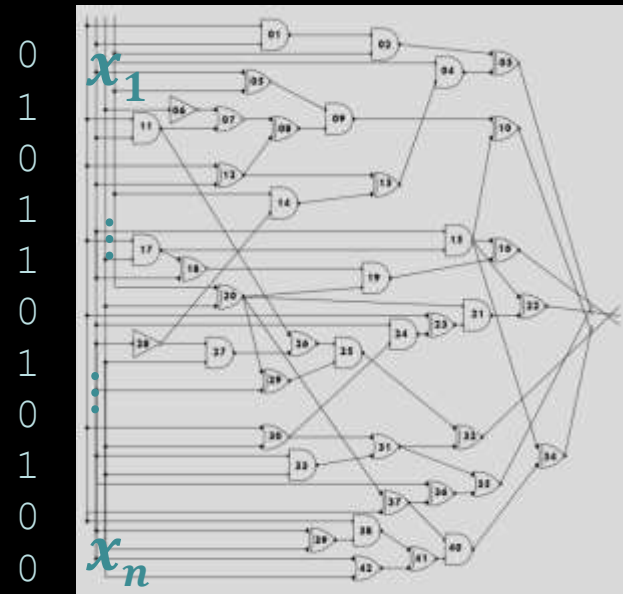
**Ryan Williams, MIT
and IAS (Princeton)**

How space-efficiently can one simulate time-efficient computations?

Every $T(n)$ -time program will use no more than (about) $T(n)$ space.

Given any $T(n)$ -time program M ,
is there always a way to reimplement M , so it uses $\ll T(n)$ space?

Canonical Problem: Circuit Evaluation / Circuit Value Problem (CVP)



Given C, x compute the output

On circuits of size s :

- about s time to solve CVP
- needs $\Omega(s)$ space, to store intermediate gate values?

[PV'76, Borodin'77]

CVP is in $O(s/\log s)$ space

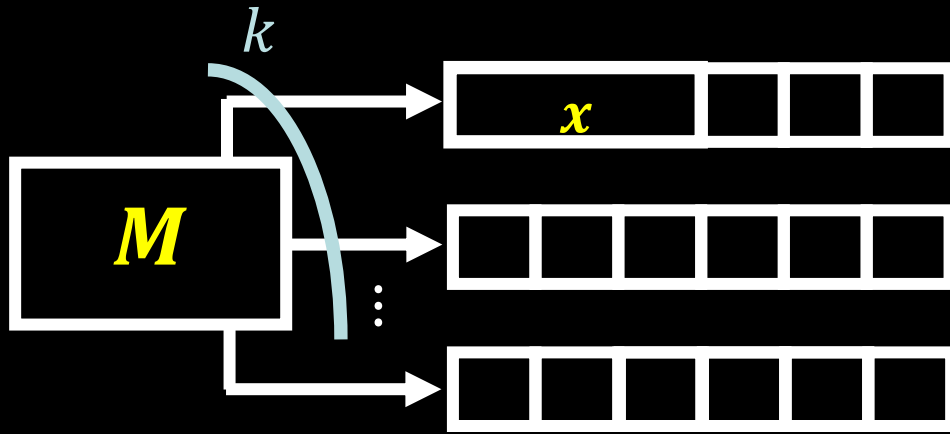
[HPV'75, PR'81, HLMW'86]

$\text{TIME}[t] \subseteq \text{SPACE}[t/\log t]$

“Pebbling approach” with an $\Omega(t/\log t)$ lower bound

[LT'79] (more later on this)

Model of Computation: Multitape Turing Machine



- read/write k cells in each step
- the k tape heads can move left/right, in each step

$\text{TIME}[T] :=$ problems solvable in $O(T(n))$ time on a MTM [HS'65]

Old model, but very robust!

Examples: CVP, Sorting, FFT are in $\text{TIME}[n \cdot \text{polylog}(n)]$,
 $n^{3-\varepsilon}$ -time matrix mult algorithms are in $\text{TIME}[n^{3-\varepsilon} \cdot \text{polylog}(n)]$, etc.
(in fact, two tapes suffice [HS'66])

Open Problem: find **any** problem solvable in $O(n)$ -time on RAMs with no $O(n \cdot \text{polylog}(n))$ -time MTM

Theorem: For all $T: \mathbb{N} \rightarrow \mathbb{N}$ with $T(n) \geq n$,
 $\text{TIME}[T] \subseteq \text{SPACE}[\sqrt{T \log T}]$

Every MTM running in time T has an equivalent MTM using $O(\sqrt{T \log T})$ space (!!)

(Now False) Conjecture: For all $\varepsilon > 0$, $\text{TIME}[T] \not\subseteq \text{SPACE}[T^{1-\varepsilon}]$

[Sipser'86] Conjecture + Explicit Expanders $\Rightarrow P = RP$

(nowadays, we know [NW'94, IW'97, ...] that we “only” need circuit lower bounds on time in order to achieve derandomization; we don't need space lower bounds on time)

Corollary: $\text{CVP} \in \text{SPACE}[\sqrt{n} \cdot \text{polylog}(n)]$

By diagonalization, we can conclude new lower bounds (towards $P \neq PSPACE$):

Corollary: For all “nice” $s(n) \geq n$, $\text{SPACE}[s] \not\subseteq \text{TIME}[s^2 / \log^2(s)]$

Corollary: There is an explicit $\Pi \in \text{SPACE}[n]$ not in $\text{TIME}[n^2 / \log^2 n]$

Can the Theorem be improved?

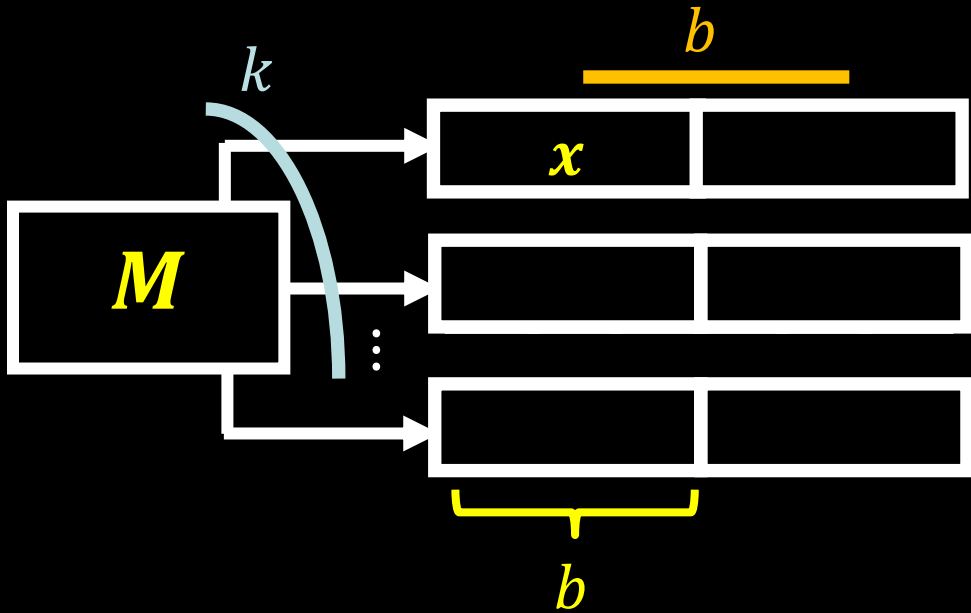
Proposition: If $\text{TIME}[T] \subseteq \text{SPACE}[T^\varepsilon]$ for all $\varepsilon > 0$, then $P \neq PSPACE$

Prior Work: $\text{TIME}[T] \subseteq \text{SPACE}[T / \log T]$

Given MTM M , input x of length n

Partition the k tapes of M into

blocks of b cells



Define a computation graph $G_{M,x}$:

nodes: $\{0, 1, \dots, T(n)/b\}$

each node represents a time interval: b steps of time

edges: for $i < j$, edge (i, j) if “info computed in interval i is needed to compute info in interval j ”

$\forall i, (i - 1, i)$ is an edge

need the last state from interval $i - 1$, to start interval i

for $i < j$, edge (i, j) if some block is visited in intervals i and j but is not visited in intervals $i + 1, \dots, j - 1$

Obs: during an interval, each tape has ≤ 2 blocks accessed

$\forall i, \text{indeg}(i) \leq \underbrace{2k}_{\text{from blocks}} + \underbrace{1}_{\text{from state}}$

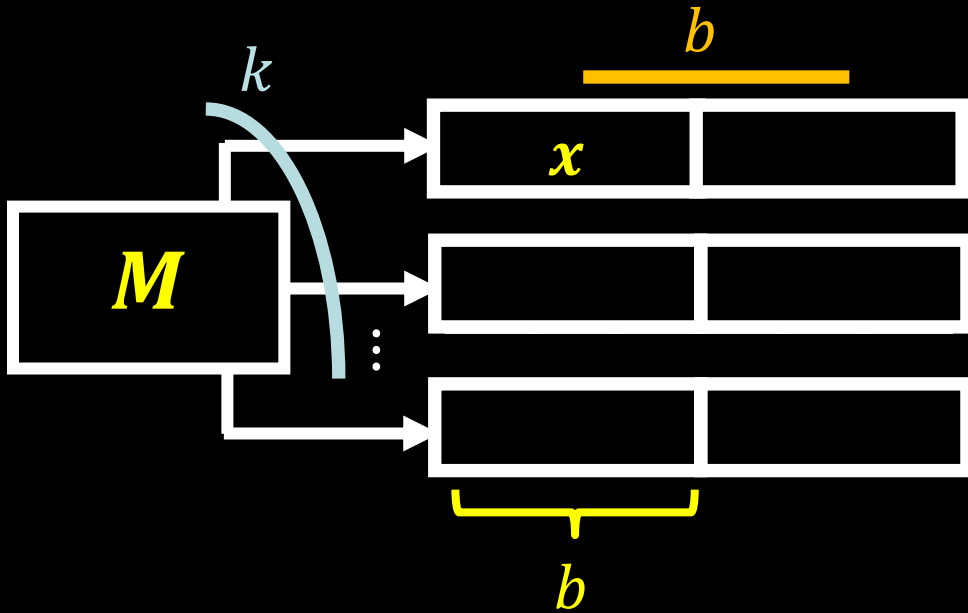
For simplicity: $T(n) \geq n^2, b \approx \sqrt{T(n)}$

Prior Work: $\text{TIME}[T] \subseteq \text{SPACE}[T / \log T]$

Given MTM M , input x of length n

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For simplicity: $T(n) \geq n^2$, $b \approx \sqrt{T(n)}$

computation graph $G_{M,x} = (V, E)$

$$V = \{0, 1, \dots, T(n)/b\}$$

for $i < j$, $(i, j) \in E$ iff “info computed in interval i is needed to compute info in interval j ”

$$\forall i, \text{indeg}(i) \leq 2k + 1$$

Define strings with the info computed in each interval:

content(0): initial configuration of M on x [$O(n)$ bits]

content(i): info computed during interval i [$O(b)$ bits]

[state + head positions at end, tape blocks accessed]

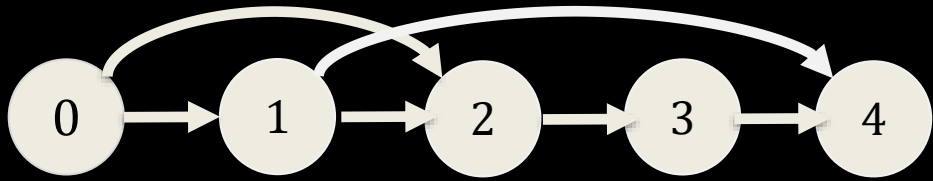
Obs: given **content(i)** for all i with $(i, j) \in E$,
can compute **content(j)** in $O(b)$ time

Goal: Determine **content($T(n)/b$)**

[contains accept/reject state!]

Prior Work: $\text{TIME}[T] \subseteq \text{SPACE}[T / \log T]$

Now we have a problem on DAGs:



Pebble Game: played on v -node graph

1. Can put pebble on source
2. Given pebbles on all i with $(i, j) \in E$, can put pebble on j
3. Can remove pebbles at any time

How many pebbles needed to put a pebble on the last node? [HPV'75,LT'79]

$\Theta(v / \log v)$ for DAGs of $O(1)$ indegree
Store only $O(T/b) / \log(T/b)$ content strings at a time $\Rightarrow O(T / \log(T/b))$ space

computation graph $G_{M,x} = (V, E)$

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Towards Low Space: The Tree Evaluation Problem (TEP)

[Braverman-Cook-McKenzie-Santhanam-Wehr'09]

Parameters $d, b, h > 0$. **Given:** d -ary tree of height h

Each inner node u is labeled by $f_u: \{0,1\}^{d \cdot b} \rightarrow \{0,1\}^b$

[each f_u is given as a table of length $2^{d \cdot b}$]

Each leaf ℓ is labeled by a value $a_\ell \in \{0,1\}^b$ [d^h values]

For an inner node u , if $a_{u_1}, \dots, a_{u_d}$ are the values of the children of u , then value of u is $a_u := f_u(a_{u_1}, \dots, a_{u_d})$

Goal: Find value of the root: $a_\varepsilon \in \{0,1\}^b$

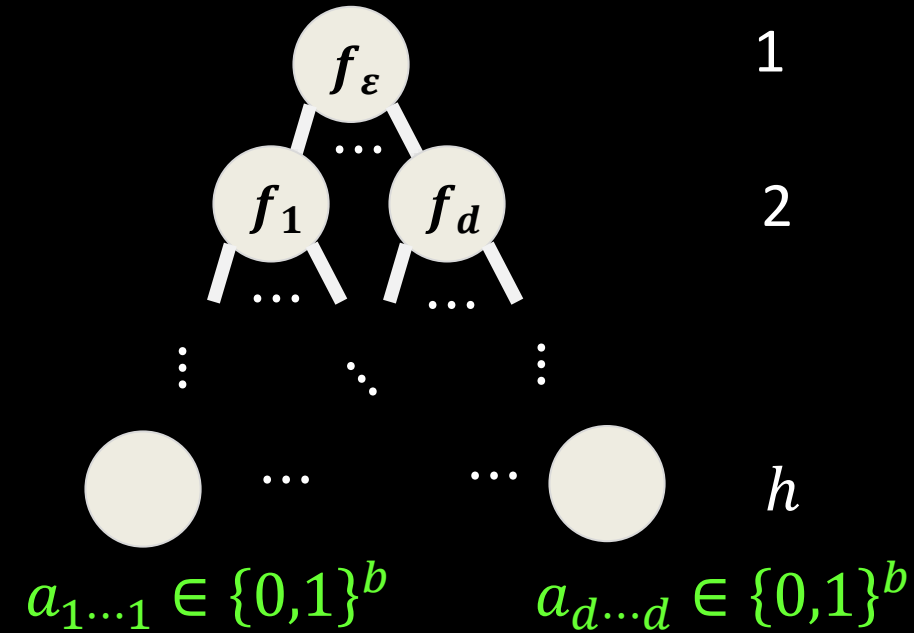
Simple recursive algorithm:

TE(v): If v is a leaf, return a_v

For $i = 1, \dots, d$, compute $A_i = \text{TE}(v_i)$

Return $f_v(A_1, \dots, A_d)$ and erase $A_1, \dots, A_d$

Takes $O(h \cdot d \cdot b)$ space $\rightarrow O(\log^2 N)$ for input length N



How much space?

[Braverman et al] showed LBs in restricted settings, conjectured
TEP $\notin$ NL

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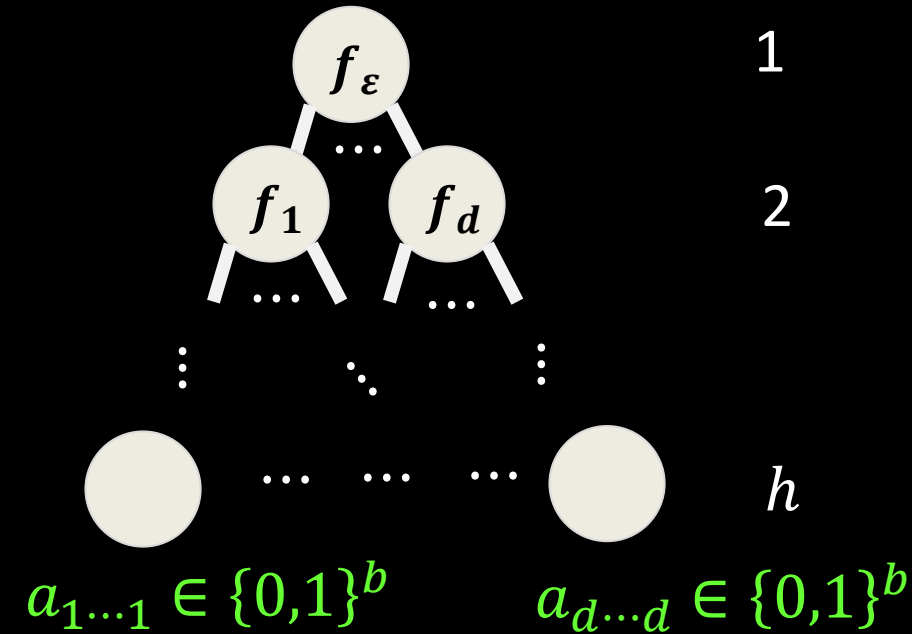
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Simple algorithm takes $O(hdb)$ space $\rightarrow$ stack of height h

[Cook-Mertz'24] TEP in $O(h \log(db) + db)$ space!

Stack of height h , with only $O(\log(db))$ bits on each level



Key Idea: The simple algorithm allocates fresh space for each value computed at each level

Instead, XOR values into existing space! Algorithm XORs the value of u into existing space, assuming an oracle that can XOR the values of u 's children into existing space.

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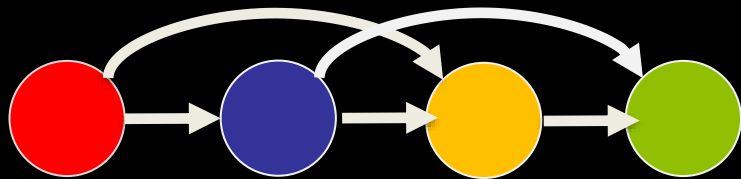
Idea: Given time- T MTM M and input x , reduce to (exp-sized) TEP instance

Assume we know $G_{M,x}$ [either it's stored in memory, or we can compute its edges efficiently]

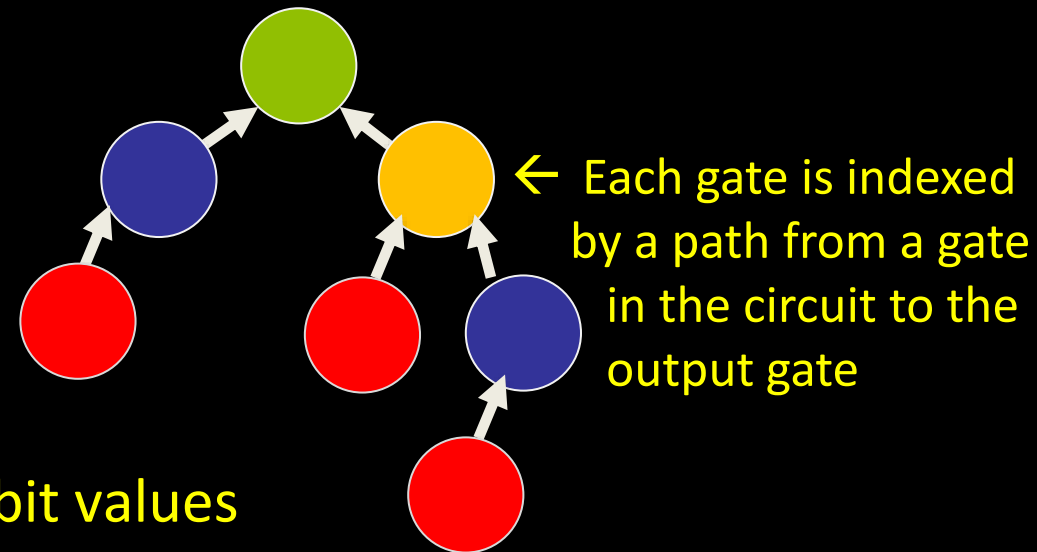
Set $d := 2k + 1$, $h := 1 + T(n)/b$, and set b so that for all i , $|\text{content}(i)| \leq b$

Extend Cook-Mertz for trees with $\leq d$ children at each node, and max height h

[Folklore] Boolean circuits of depth $h \quad \mapsto \quad$ Boolean formulas of depth h



$\mapsto$



This transformation works just as well for circuits and formulas with b -bit values on the wires

Computing content in $G_{M,x}$ is evaluating a circuit over b -bit values

TEP $\equiv$ Evaluating a formula over b -bit values of depth h and fan-in d

Theorem: For $T: \mathbb{N} \rightarrow \mathbb{N}$ with $T(n) \geq n^2$, $\text{TIME}[T] \subseteq \text{SPACE}[\sqrt{T} \cdot \log(T)]$

Idea: Given time- T MTM M and input x , reduce to (exp-sized) TEP instance

Assume we know $G_{M,x}$ [either it's stored in memory, or we can compute its edges efficiently]

Set $d := 2k + 1$, $h := 1 + T(n)/b$, and set b so that for all i , $|\text{content}(i)| \leq b$

We can evaluate $\text{content}(T(n)/b)$ of $G_{M,x}$ using the Cook-Mertz procedure!

Space of Cook-Mertz: $O(d \cdot b + h \cdot \log(d \cdot b)) \leq O(b + (T \log b)/b)$

set b to minimize $\rightarrow O(\sqrt{T \log T})$ space

BUT! We don't know $G_{M,x}$...

Easiest fix: Program M so that we can calculate all head positions quickly (in advance)

Def. M is oblivious if $\forall n$ and x of length n , head movements of M on x only depend on n

Thm [HS'66, PF'79] For all MTM M in $T(n)$ time, there's an **equivalent** two-tape oblivious M' that runs in $O(T(n) \log T(n))$ time. Given n, i in binary, head positions of M' at step i can be computed in **$\text{poly}(\log T(n))$ time**. $\rightarrow$ Can calculate $G_{M',x}$! (But we lose a little)

Open Problems

- **Extend to RAMs?** (Show $TIME_{RAM}(T) \subseteq SPACE(T^{1-\varepsilon})$?)
- **Extend to Parallel Machines?** (Show $TIME(T) \subseteq ATIME(T^{1-\varepsilon})$?)
Would imply super-linear time lower bounds for problems like Quantified Boolean Formulas!
- $TIME(T) \subseteq SPACE(T^{0.5-\varepsilon})$? *This would resolve the first two!*
Improve this bound for single-tape Turing machines!
- **Barrier?**

I'm very lucky that I found this reduction *after* Cook-Mertz, or I would have definitely declared the reduction to be a “barrier”...

*“You can't solve Tree Eval in much less space, or you'd improve HPV...
...which we **know** you can't do”*

Thank you!



image courtesy of ChatGPT